

ECE/ENGRD 2100

Introduction to Circuits for ECE

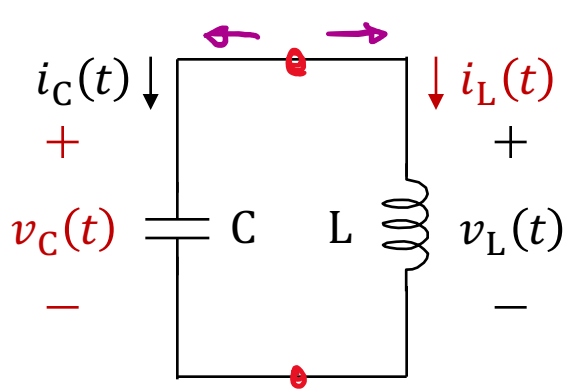
Lecture 20

Undamped Second Order LC Circuits Natural Response

Announcements

- Recommended Reading:
 - Textbook Chapter 8
- Upcoming due dates:
 - Homework 3 due by 11:59 pm on Monday March 11, 2019
 - Lab report 3 due by 11:59 pm on Friday March 15, 2019
- Prelim 2 on Thursday March 28, 2019 from 7:30 – 9 pm in 203 Phillips
 - Email afridi@cornell.edu if have conflict
 - Will cover material through Lecture 24
 - Prelim is closed-book and closed-notes
 - Two double-sided page formula sheet is allowed
 - Bring a calculator

Undriven LC Circuit – Differential Equation Approach



$$i_C = -i_L$$

$$\underline{\text{KVL}} \Rightarrow v_C = v_L$$

$$\Rightarrow v_C = L \frac{di_L}{dt}$$

$$\Rightarrow \frac{dv_C}{dt} = L \frac{d^2 i_L}{dt^2}$$

$$-\frac{i_L}{C} = L \frac{d^2 i_L}{dt^2}$$

$$\Rightarrow \boxed{LC \frac{d^2 i_L}{dt^2} + i_L = 0}$$

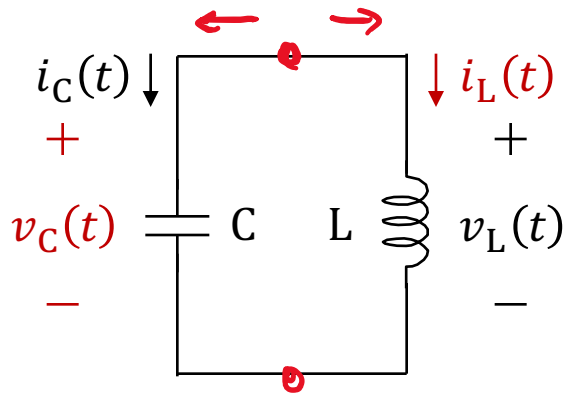
$$v_L = L \frac{di_L}{dt}$$

$$i_C = C \frac{dv_C}{dt}$$

$$\frac{dv_C}{dt} = \frac{i_C}{C} = -\frac{i_L}{C}$$

Diff. Eq. in terms of i_L

Undriven LC Circuit – Alternate Differential Equation



$$i_C = C \frac{dv_C}{dt}$$

$$i_C = -i_L$$

$$C \frac{dv_C}{dt} = -i_L$$

$$C \frac{d^2 v_C}{dt^2} = -\frac{di_L}{dt}$$

$$v_L = L \frac{di_L}{dt}$$

$$v_L = v_C$$

$$\frac{di_L}{dt} = \frac{v_C}{L}$$

$$C \frac{d^2 v_C}{dt^2} = -\frac{v_C}{L}$$

$$LC \frac{d^2 v_C}{dt^2} + v_C = 0$$

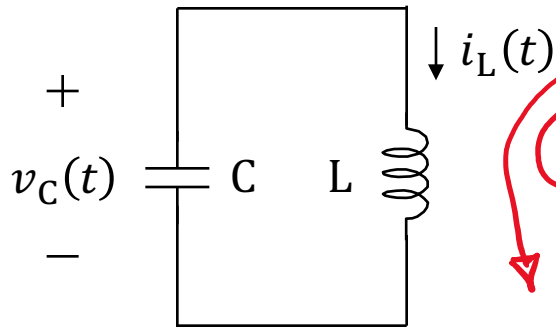
Differential equation in terms of v_C

$$LC \frac{d^2 i_L}{dt^2} + i_L = 0$$

Can Use either

Differential equation in terms of i_L

LC Circuit – Natural Response



$$LC \frac{d^2 v_C}{dt^2} + v_C = 0$$

← Homogeneous Eq
Particular Solu = 0
↑
Driven Response
(No drive)

$v_{C,h} = Ae^{st}$ ← Homogeneous Solution

~~$LCAs^2 e^{st} + Ae^{st} = 0$~~

$$\Rightarrow s^2 = -\frac{1}{LC}$$

\Rightarrow

$$s = \pm \frac{\sqrt{-1}}{\sqrt{LC}}$$

$j \equiv \sqrt{-1}$

$$\Rightarrow s = \pm \frac{j}{\sqrt{LC}}$$

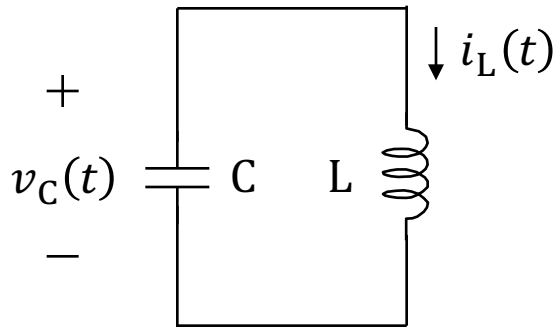
$$\Rightarrow s = +j\omega_0 \text{ or } s = -j\omega_0$$

Define $\frac{1}{\sqrt{LC}} \equiv \omega_0$

$v_{C,h}(t) = A_1 e^{+j\omega_0 t} + A_2 e^{-j\omega_0 t}$

Undamped Natural Radial Frequency, ω_0

LC Circuit – Natural Response – Capacitor Voltage



$$v_C(t) = v_{C,h}(t) + v_{C,p}(t) = A_1 e^{j\omega_0 t} + A_2 e^{-j\omega_0 t}$$

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$v_C(t) = A_1 \cos(\omega_0 t) + j A_1 \sin(\omega_0 t) + A_2 \cos(-\omega_0 t)$$

$$A_2 \cos(\omega_0 t) + j A_2 \sin(-\omega_0 t)$$

$$-j A_2 \sin(\omega_0 t)$$

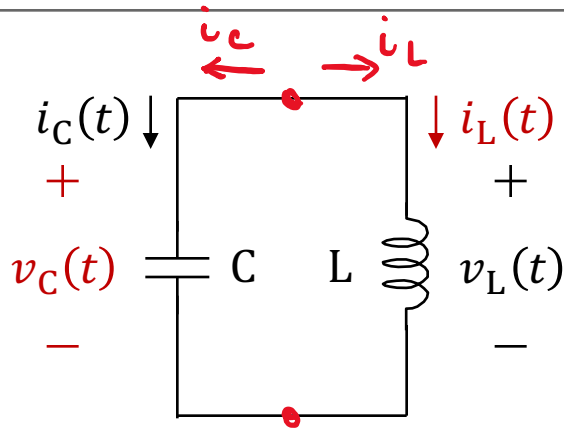
$$v_C(t) = \underbrace{(A_1 + A_2)}_{B_1} \cos(\omega_0 t) + j \underbrace{(A_1 - A_2)}_{B_2} \sin(\omega_0 t)$$

B_1 & B_2 will be real

$$v_C(t) = B_1 \cos(\omega_0 t) + B_2 \sin(\omega_0 t) = B \cos(\omega_0 t + \phi)$$

Undamped Natural \uparrow Radial Freq.

LC Circuit – Natural Response – Inductor Current



$$v_C(t) = B_1 \cos(\omega_0 t) + B_2 \sin(\omega_0 t) = B \cos(\omega_0 t + \phi)$$

$$i_L(t) = -i_C = -C \frac{dv_C}{dt}$$

$$i_L(t) = +C B \omega_0 \sin(\omega_0 t + \phi)$$

Initial Conditions

$$v_C(0) = V_0 \neq i_L(0) = I_0$$

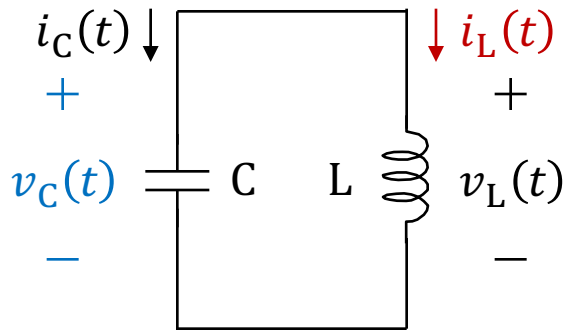
$$C \omega_0 = C \frac{1}{\sqrt{LC}} = \sqrt{\frac{C}{L}} = \frac{1}{Z_0}$$

$$i_L(t) = \frac{B}{Z_0} \sin(\omega_0 t + \phi)$$

Define $Z_0 \equiv \sqrt{\frac{L}{C}}$

Characteristic Impedance, Z_0

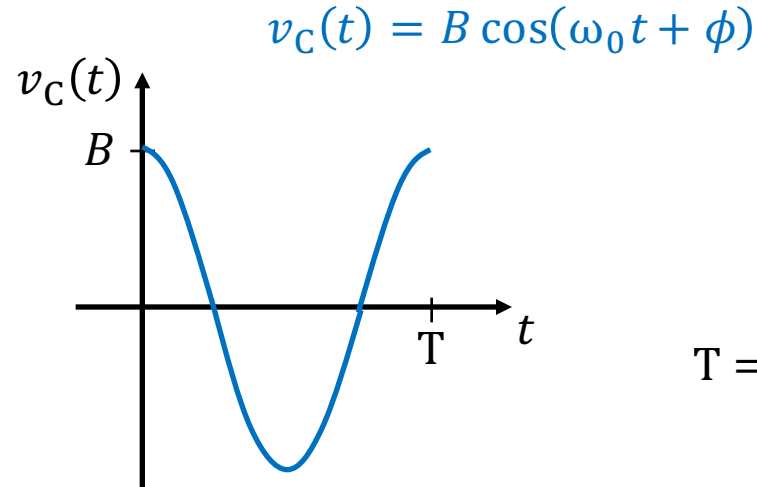
LC Circuit – Natural Response Summary



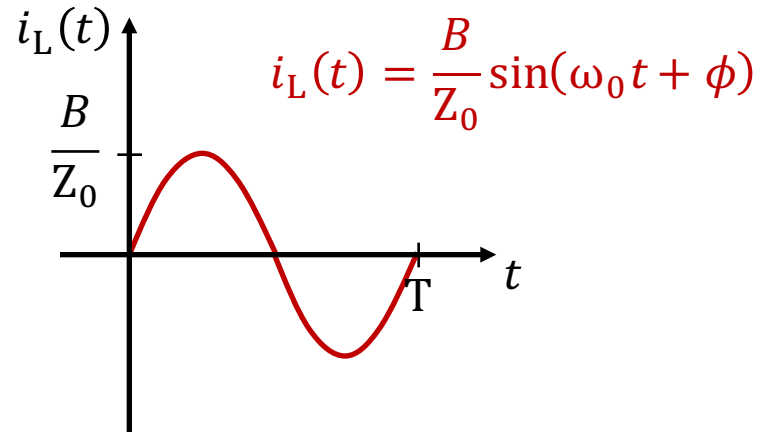
$v_L = L \frac{di_L}{dt}$
 Cos ← Sin →

$i_C = C \frac{dv_C}{dt}$
 Cos ← Sin →

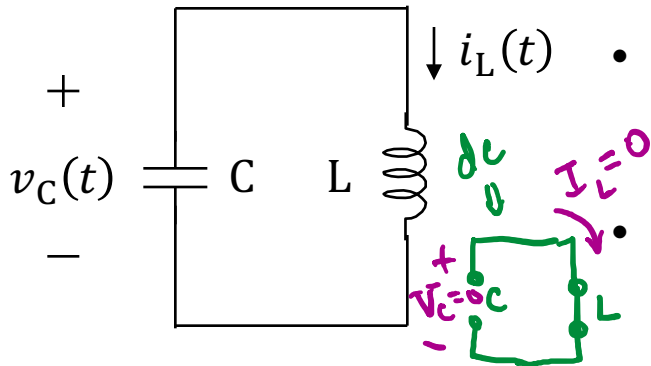
Voltage → current → current → voltage
 ELI the ICE man
 ↑ ↑
 Inductor Capacitor



$$T = \frac{1}{f_0} = \frac{2\pi}{\omega_0}$$



Undriven LC Circuit – Intuitive Approach



- Since there is no energy dissipating element in the circuit, $v_C(t)$ and $i_L(t)$ will oscillate without damping
- For total energy to remain constant, $v_C(t)$ and $i_L(t)$ oscillations must remain 90° out of phase

- Voltage of an inductor always leads its current, $v_L (= v_C)$ must lead i_L , i.e., if v_C oscillation is \cos then i_L oscillation is \sin (as \cos leads \sin by 90°)
- To determine dc value $v_C(t)$ and $i_L(t)$ will oscillate around: V_C, I_L , assume circuit has a little damping, then ask what values of $v_C(t)$ and $i_L(t)$ would the circuit settle down to – $v_C(t)$ and $i_L(t)$ will oscillate around these values.

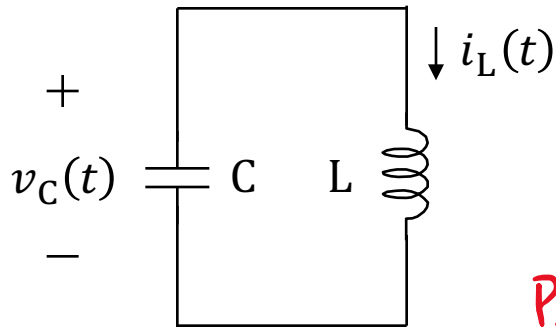
- Frequency of oscillation, $\omega_0 = 1/\sqrt{LC}$

- Relationship between amplitudes of oscillations of v_C and i_L is given by $\Delta V_C = Z_0 \Delta I_L$ where $Z_0 = \sqrt{L/C}$

$$v_C(t) = B \cos(\omega_0 t + \phi) + 0 \quad \begin{matrix} V_C \\ \text{"} \\ I_L \end{matrix}$$

$$i_L(t) = \frac{B}{Z_0} \sin(\omega_0 t + \phi) + 0 \quad \begin{matrix} V_C \\ \text{"} \\ I_L \end{matrix}$$

Relationship Between Amplitudes of Oscillations



Capacitor voltage amplitude of oscillation $\equiv \Delta V_C$

Inductor current amplitude of oscillation $\equiv \Delta I_L$

$$\text{Peak Energy in Capacitor} = \frac{1}{2} C \Delta V_C^2$$

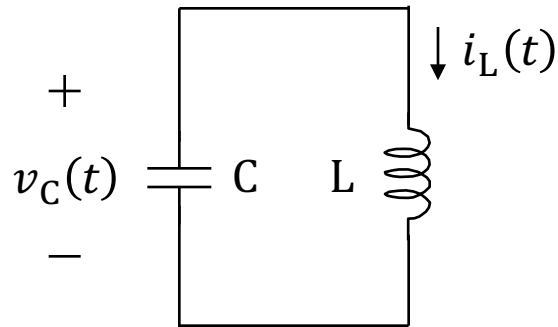
$$\text{Peak Energy in Inductor} = \frac{1}{2} L \Delta I_L^2$$

$$\text{Energy Conservation: } \frac{1}{2} C \Delta V_C^2 = \frac{1}{2} L \Delta I_L^2$$

$$\Rightarrow \frac{\Delta V_C}{\Delta I_L} = \sqrt{\frac{L}{C}} = Z_0$$

$$\Delta V_C = Z_0 \Delta I_L$$

Undriven LC Circuit – Applying Initial Conditions



$$v_C(0^+) = V_0 \quad i_L(0^+) = I_0$$

$$v_C(t) = B \cos(\omega_0 t + \phi) \Rightarrow v_C(0^+) = B \cos \phi$$

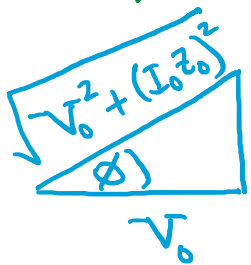
$$i_L(t) = \frac{B}{Z_0} \sin(\omega_0 t + \phi) \Rightarrow i_L(0^+) = \frac{B}{Z_0} \sin \phi$$

$$B \cos \phi = V_0$$

$$\frac{B}{Z_0} \sin \phi = I_0$$

$$\Rightarrow \frac{\cancel{B} \sin \phi}{\cancel{B} \cos \phi} = \frac{I_0}{V_0} \Rightarrow \tan \phi = \frac{I_0 Z_0}{V_0}$$

$$\phi = \tan^{-1} \left(\frac{I_0 Z_0}{V_0} \right)$$



$$\Rightarrow \cos \phi = \frac{V_0}{\sqrt{V_0^2 + (I_0 Z_0)^2}}$$

$$\therefore B = \frac{V_0}{\cos \phi} = \cancel{V_0} \cdot \frac{\sqrt{V_0^2 + (I_0 Z_0)^2}}{\cancel{V_0}} \Rightarrow$$

$$B = \sqrt{V_0^2 + (I_0 Z_0)^2}$$