

ECE/ENGRD 2100

Introduction to Circuits for ECE

Lecture 19

Step Response and Impulse Response

Announcements

- Recommended Reading:
 - Textbook Chapter 7
- Upcoming due dates:
 - Homework 3 due by 11:59 pm on Monday March 11, 2019
 - Lab report 3 due by 11:59 pm on Friday March 15, 2019
- Prelim 2 on Thursday March 28, 2019 from 7:30 – 9 pm in 203 Phillips
 - Email afridi@cornell.edu if have conflict
 - Will cover material through Lecture 24
 - Prelim is closed-book and closed-notes
 - Two double-sided page formula sheet is allowed
 - Bring a calculator

Unit Step Function

unit step $t=0$

$$u(t) = \begin{cases} 0 & \text{for } t < 0 \\ 1 & \text{for } t > 0 \end{cases}$$

transition

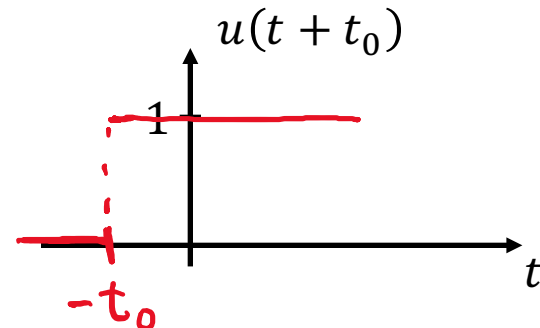
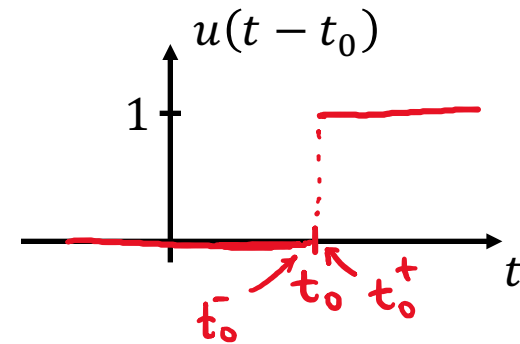
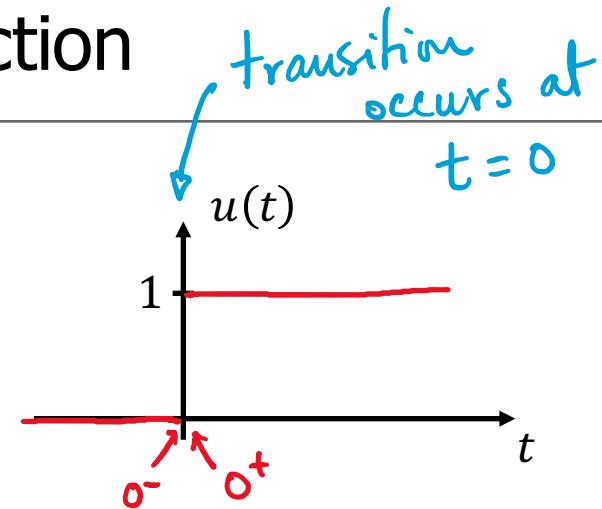
$$t - t_0 = 0 \Rightarrow t = t_0$$

$$u(t - t_0) = \begin{cases} 0 & \text{for } t < t_0 \\ 1 & \text{for } t > t_0 \end{cases}$$

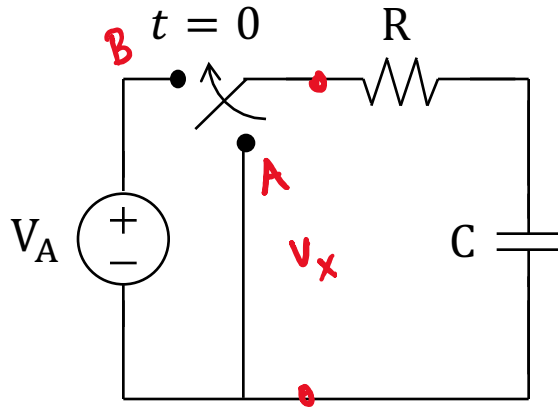
$$t + t_0 = 0 \Rightarrow t = -t_0$$

$$u(t + t_0) = \begin{cases} 0 & \text{for } t < -t_0 \\ 1 & \text{for } t > -t_0 \end{cases}$$

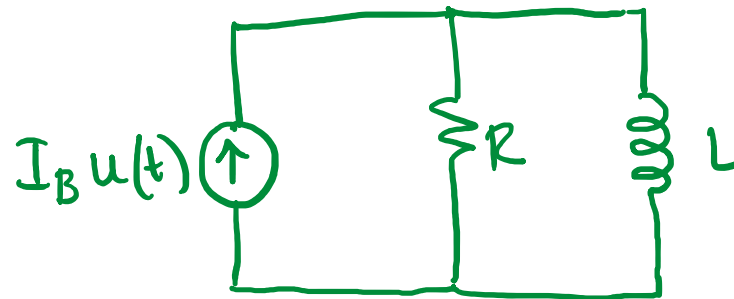
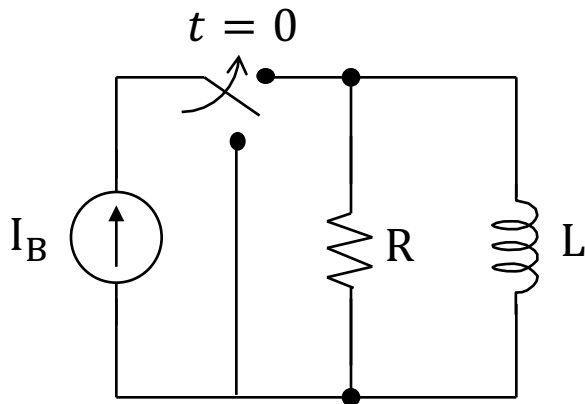
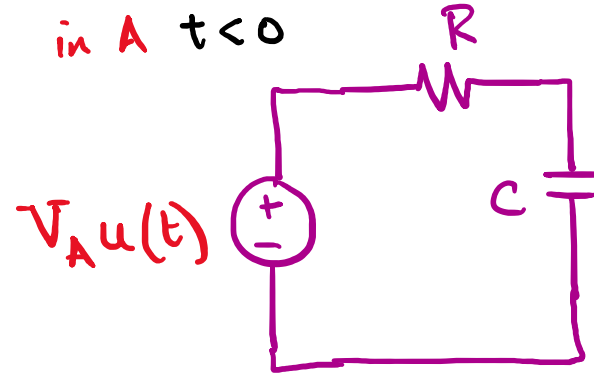
$u(t)$ is unit-less



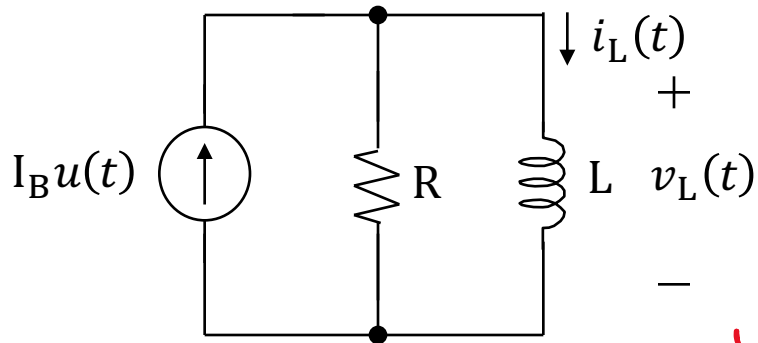
Modeling Switch Action using Unit Step



$$v_x = \begin{cases} V_A & \text{in B } t > 0 \\ 0 & \text{in A } t < 0 \end{cases}$$

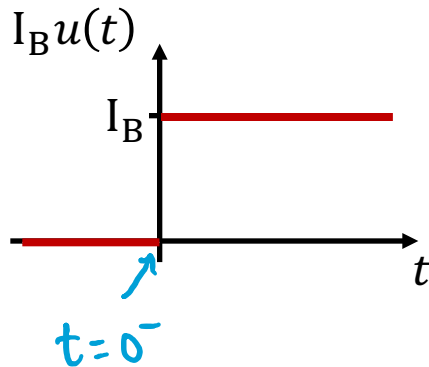


Step Response Example



Find $v_L(t)$ for all t

Find $i_L(t)$ first since can apply continuity condition to it

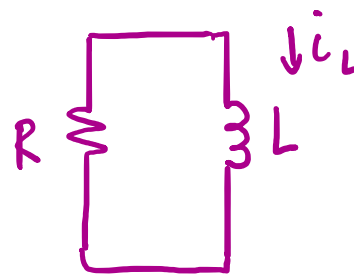


$$v_L = L \frac{di_L}{dt}$$

$$\boxed{\begin{matrix} i_L(0^-) \\ = \\ 0 \end{matrix}}$$

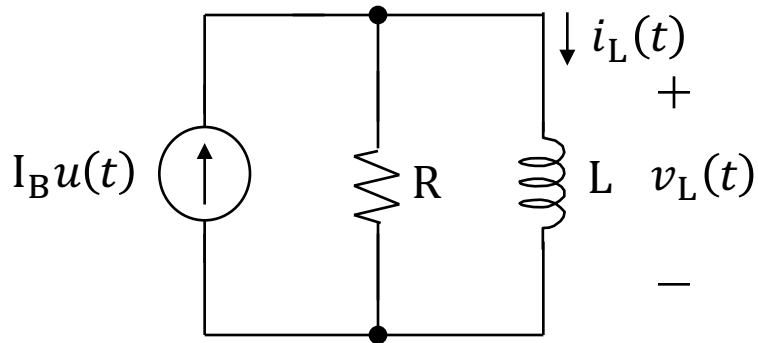
$t < 0$

$$i_L(t < 0) = 0$$



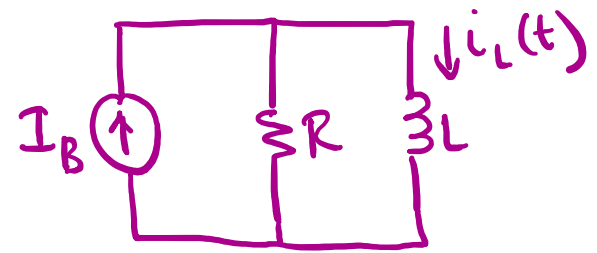
$i_L(0^+) = i_L(0^-) = 0$ ← Initial Condition for $t > 0$

Step Response Example (Cont.)

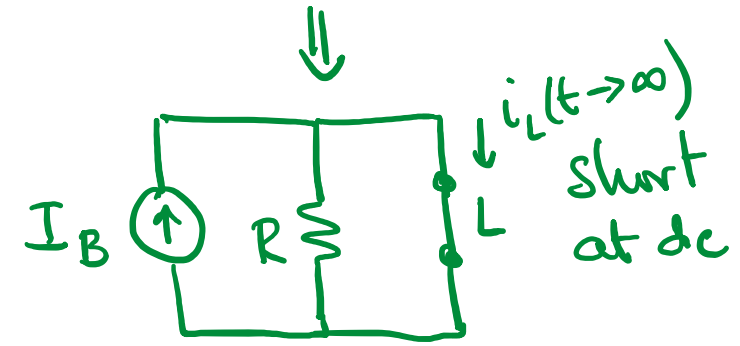


$i_L(0^+) = 0$

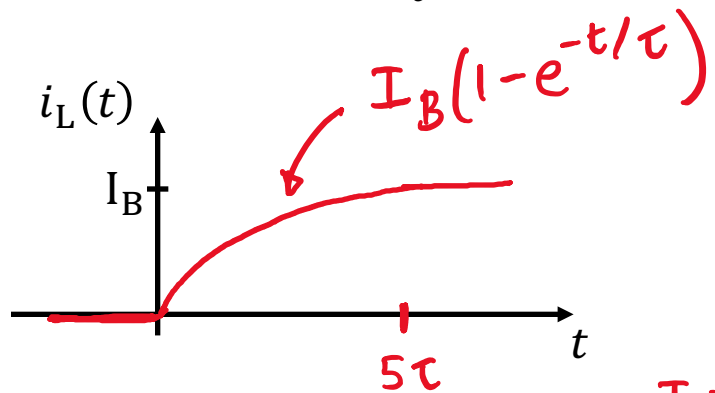
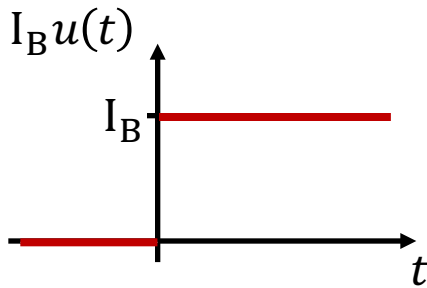
$t > 0$



$t \rightarrow \infty$

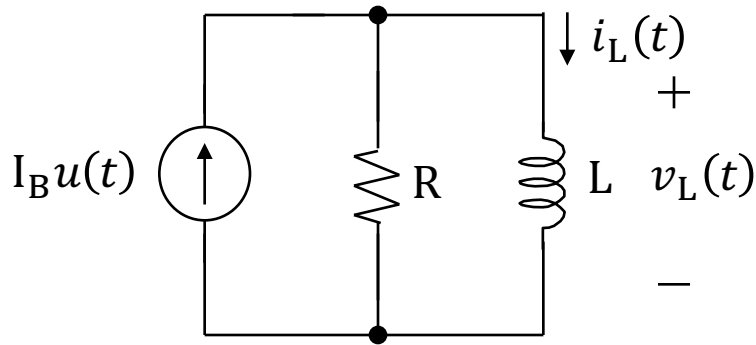


$i_L(t \rightarrow \infty) = I_B$



$\tau = \frac{L}{R}$

Step Response Example (Cont.)



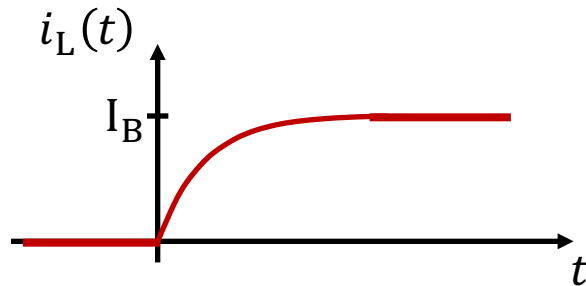
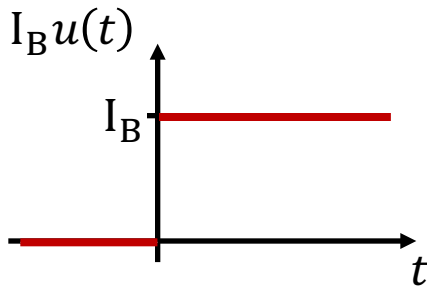
$$i_L(t) = \begin{cases} 0 & \text{for } t < 0 \\ \underline{I_B(1 - e^{-t/\tau})} & \text{for } t > 0 \end{cases}$$

$$v_L = L \frac{di_L}{dt} \Rightarrow v_L = 0 \quad t < 0$$

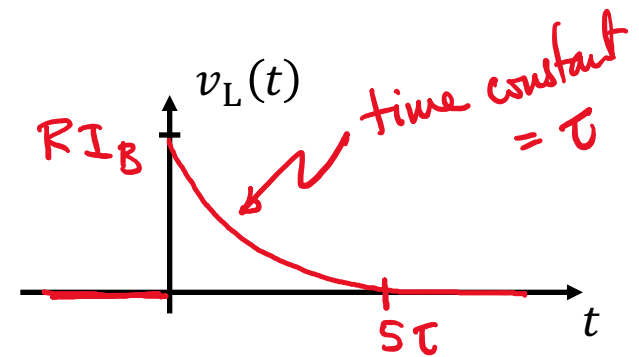
$t > 0$

$$v_L = L I_B \left(+ e^{-t/\tau} \right) \left(-\frac{1}{\tau} \right) = \cancel{L} I_B e^{-t/\tau} \frac{R}{\cancel{L}}$$

$$\underline{v_L = R I_B e^{-t/\tau}} \quad t > 0$$



Inductor looks like an open circuit under fast transients



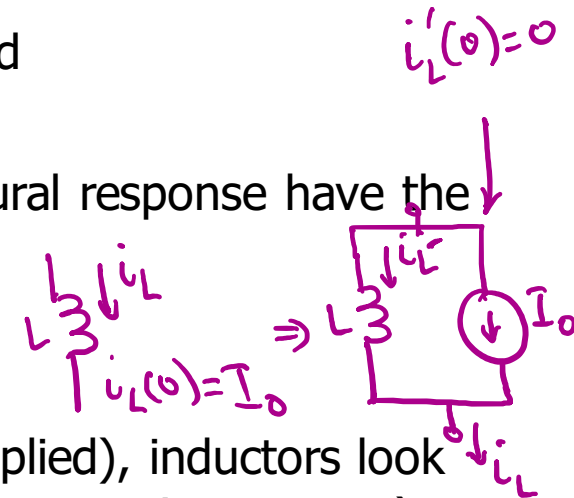
Key Lessons

- Continuity applies to state variables: $i_L(t)$ and $v_C(t)$ ←
– But not to other currents and voltages in the circuit

- Best to first solve for state variables
– Other currents and voltages can then be determined

- All voltages and currents in a circuit that undergo natural response have the same time constant

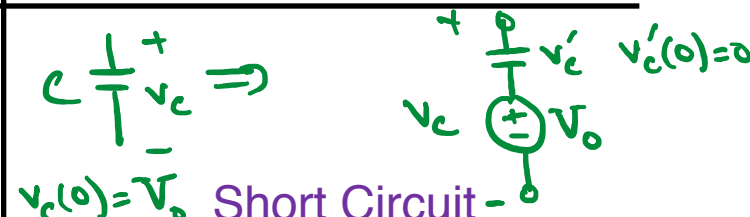
- In dc steady state, inductors look like short circuit
– But during abrupt transitions (e.g., when step is applied), inductors look like an open circuit (or a current source if inductor current is non-zero)



- In dc steady state, capacitors look like open circuit
– But during abrupt transitions (e.g., when step is applied), capacitors look like a short circuit (or a voltage source if capacitor voltage is non-zero)

$$i_c = C \frac{dv_c}{dt}$$

DC Steady State versus Fast Transient Behavior

	DC Steady State	Fast Transient
Capacitor	Open Circuit	 <p>Short Circuit</p> <p>or voltage source of voltage equal to its initial voltage</p>
Inductor	Short Circuit	<p>Open Circuit</p> <p>or current source of current equal to its initial current</p>

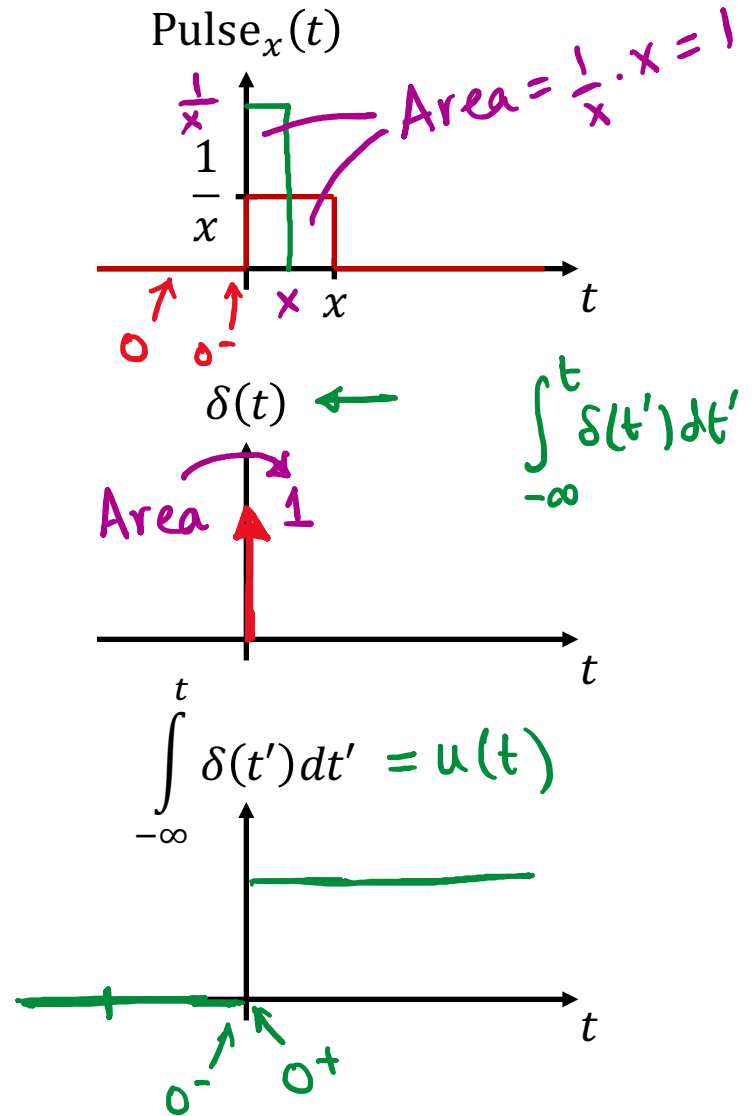
Impulse Function

Pulse_x(t) → δ(t)
 x → 0

$$\int_{-\infty}^t \delta(t') dt' = u(t)$$

$$\delta(t) = \frac{du(t)}{dt}$$

δ(t) has units of s⁻¹



Current Impulse and Voltage Impulse

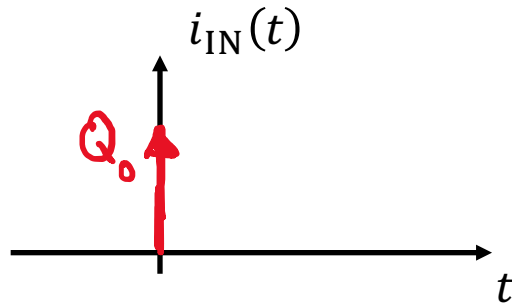
Current Impulse

$$i_{IN}(t) = Q_0 \delta(t) \quad [\text{A}]$$

charge

$C = A \cdot s$

s^{-1}



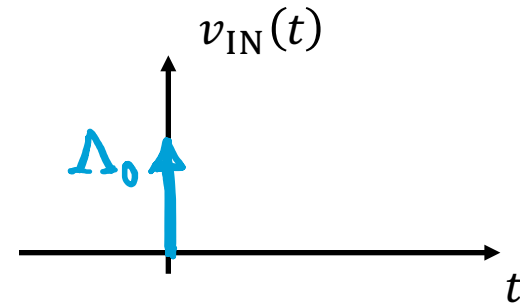
Voltage Impulse

$$v_{IN}(t) = \Lambda_0 \delta(t) \quad [\text{V}]$$

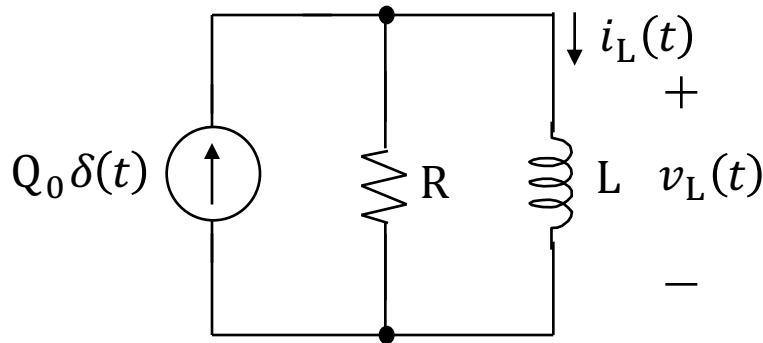
Flux Linkage

$V \cdot s$

s^{-1}

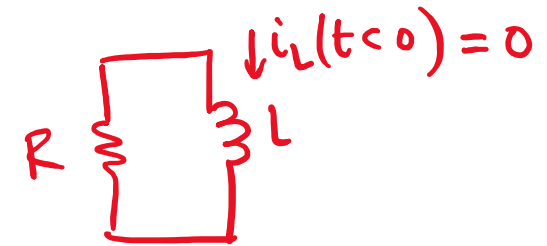


Impulse Response Example



Find $i_L(t)$ for all t

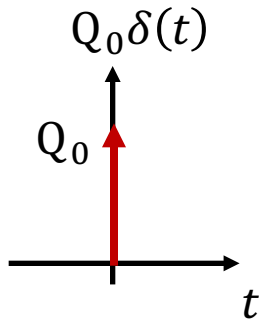
$t < 0$



$i_L(0^-) = 0$

$v_L(0) = Q_0 \delta(t) R$

$i_L(0^+) = ?$

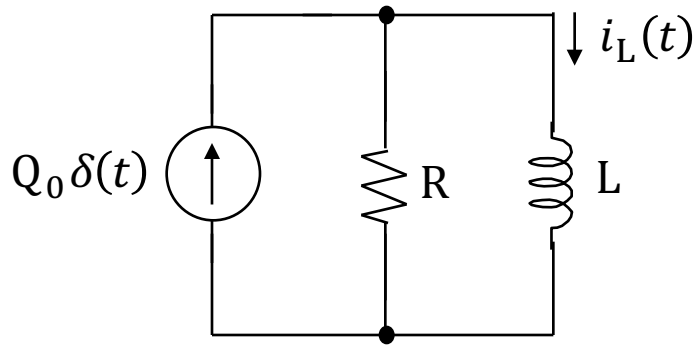


$v_L = L \frac{di_L}{dt} \Rightarrow i_L(t) = \frac{1}{L} \int_{-\infty}^t v_L(t') dt' = \frac{1}{L} \int_{0^-}^t v_L(t') dt'$

$i_L(0^+) = \frac{1}{L} \int_{0^-}^{0^+} v_L(t') dt' = \frac{1}{L} \int_{0^-}^{0^+} Q_0 R \delta(t') dt' = \frac{Q_0 R}{L} \int_{0^-}^{0^+} \delta(t') dt'$

$i_L(0^+) = \frac{Q_0 R}{L}$

Impulse Response Example (cont.)



$$i_L(t) = Ke^{-t/\tau} \quad \text{for } t > 0$$

$$i_L(0^+) = \frac{Q_0 R}{L}$$

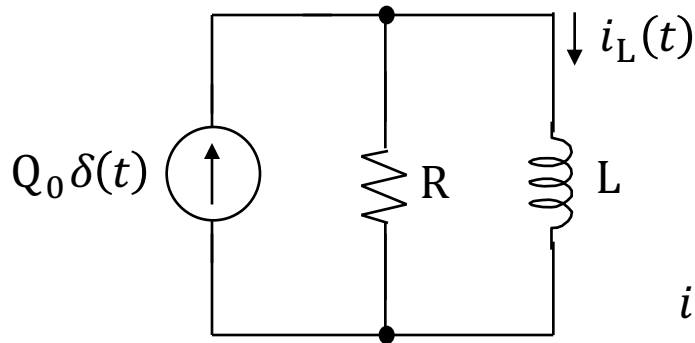
$$i_L(0^+) = K$$

$$\Rightarrow K = \frac{Q_0 R}{L}$$

$$\therefore i_L(t) = \frac{Q_0 R}{L} e^{-t/\tau}$$

$$\tau = \frac{L}{R}$$

Impulse Response Example (cont.)



$$i_L(t) = Ke^{-t/\tau} \quad \text{for } t > 0$$

$$i_L(0^+) = \frac{Q_0 R}{L}$$

$$i_L(t) = \frac{Q_0 R}{L} e^{-t/\tau} \quad \text{for } t > 0$$

