

# ECE3140 / CS3420

# Embedded Systems

## Locks

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# Dekker's Algorithm (*T. Dekker, 1966*)

P1 :

```
NCS1;
```

```
x1=1;
```

```
while (x2) {  
    if (turn!=1) x1=0;  
    while (turn!=1);  
    x1=1;  
}
```

```
CS1;
```

```
x1=0;turn=2;
```

P2 :

```
NCS2;
```

```
x2=1;
```

```
while (x1) {  
    if (turn!=2) x2=0;  
    while (turn!=2);  
    x2=1;  
}
```

```
CS2;
```

```
x2=0;turn=1;
```

## Weaknesses?

# Outline

- Lock: a synchronization primitive to efficiently support mutual exclusion
- Definition and usage example
- Implementation
  - Atomic read-modify-write instructions
  - Spinlocks
  - Blocking locks
- Building higher-level constructions using locks

# New Abstraction: Locks

- A lock  $l$  supports two basic operations:
  - $\text{lock}(l)$  (sometimes called acquiring a lock)
  - $\text{unlock}(l)$  (sometimes called releasing a lock)

P1 :

*NCS1;*

$\text{lock}(l);$

*CS1;*

$\text{unlock}(l);$

P2 :

*NCS2;*

$\text{lock}(l);$

*CS2;*

$\text{unlock}(l);$

# Why Use a Variable ('l')?

- What if there are multiple resources that need to be protected with a lock?

```
P1 :  
    lock ( ) ;  
    x=x+1 ;  
    unlock ( ) ;  
    :  
    lock ( ) ;  
    y=y+1 ;  
    unlock ( ) ;
```

```
P2 :  
    lock ( ) ;  
    x=x+1 ;  
    unlock ( ) ;  
    :  
    lock ( ) ;  
    y=y+1 ;  
    unlock ( ) ;
```

Note: the lock variable (l) is NOT a variable that the lock is protecting!

# Deadlock

- Consider nested locks

P1

```
    :  
lock (a) ;  
lock (b) ;  
CS1 ;  
unlock (b) ;  
unlock (a) ;  
    :
```

P2

```
    :  
lock (b) ;  
lock (a) ;  
CS2 ;  
unlock (a) ;  
unlock (b) ;  
    :
```

# Atomicity through Disabling Interrupts

- Timer interrupts are used to switch between processes
  - To avoid that, disable interrupts!
- On a uni-processor system, small atomic actions can be performed by disabling interrupts
  - No interrupt within a critical section
- Not a good solution in general

# Broken Mutual Exclusion Algorithm

P1 :

*NCS1;*

while (x2) ;

x1=1;

*CS1;*

x1=0;

P2 :

*NCS2;*

while (x1) ;

x2=1;

*CS2;*

x2=0;



# Atomic Read-Modify-Write Instruction

- Mutual exclusion can be implemented using ordinary load and store instructions
  - However, protocols for mutual exclusion are difficult to design...
- Simpler solution:
  - *Atomic read-modify-write instructions*

Examples: *m* is a memory location, *R* is a register

```
Test&Set (m), R:  
R ← M[m];  
if R==0 then  
    M[m] ← 1;
```

```
Fetch&Add (m), Rv, R:  
R ← M[m];  
M[m] ← R + Rv;
```

```
Swap (m), R:  
Rt ← M[m];  
M[m] ← R;  
R ← Rt;
```

# Blocking Locks

- Avoid unnecessary spinning
  - If another process owns a lock, suspend a process
    - Maintain a list of blocked processes for each lock
  - Wake up a waiting process when a lock is released

# Higher-Level Constructs

Locks can be used to build higher-level constructs

## Example: Readers and Writers

- Two types of processes
  - Reader: reads a shared resource
  - Writer: modifies a shared resource
- Safety goals:
  - Reads and writes are mutually exclusive
  - Writes are mutually exclusive
- Provide:
  - `enter_r, exit_r`
  - `enter_w, exit_w`

# Approach

- A simple approach: two shared variables
  - **nw**: number of writers
  - **nr**: number of readers

# Enter

```
enter_r:
    lock(m);
    while (nw) {
        unlock(m);
        while (nw);
        lock(m);
    }
    nr=nr+1;
    unlock(m);
```

```
enter_w:
    lock(m);
    while (nw>0 || nr>0) {
        unlock(m);
        while (nw>0 || nr>0);
        lock(m);
    }
    nw=1;
    unlock(m);
```