

(Home Work #2 Solutions) Farhan Rana

2.1 $U_k = \frac{\hbar \Omega_{RK}}{2}$

a) $|\psi(t)\rangle = c_0(t)|e_0\rangle + \sum_k c_k(t)|e_k\rangle \langle e_k|$

Plug in $i\hbar \frac{d}{dt} |\psi(t)\rangle = \hat{H} |\psi(t)\rangle$ to get

$$i\hbar \frac{d c_0(t)}{dt} |e_0\rangle + \sum_k i\hbar \frac{d c_k(t)}{dt} |e_k\rangle = \left\{ c_0(t) \epsilon_0 - \sum_k U_k e^{i\omega t} c_k(t) \right\} |e_0\rangle + \sum_k \left\{ \epsilon_k - U_k e^{-i\omega t} c_0(t) \right\} |e_k\rangle$$

Take the inner product with first $\langle e_0|$ and then $\langle e_k|$ to get the desired results.

b) $c_0(t) = b_0(t) e^{-i \frac{\epsilon_0 t}{\hbar}}$ $c_k(t) = b_k(t) e^{-i \frac{\epsilon_k t}{\hbar}}$

The idea behind this substitution is to define $b_0(t)$ and $b_k(t)$ such that all the fast time dependence of $c_0(t)$ and $c_k(t)$ is explicitly factored out. The procedure is simple and so will not be repeated here.

c) we have:

$$\frac{d b_0(t)}{dt} = \sum_k i \frac{U_k}{\hbar} e^{-i \frac{(\epsilon_k - \epsilon_0 - \hbar\omega)t}{\hbar}} b_k(t) \quad \text{--- (1)}$$

$$\frac{d b_k(t)}{dt} = i \frac{U_k}{\hbar} e^{i \frac{(\epsilon_k - \epsilon_0 - \hbar\omega)t}{\hbar}} b_0(t) \quad \text{--- (2)}$$

Solve (2) first $\left\{ \text{initial condition } b_k(t=0) = 0 \right\}$

$$b_k(t) = i \frac{U_k}{\hbar} \int_0^t dt' \left\{ e^{i \frac{(\epsilon_k - \epsilon_0 - \hbar\omega)t'}{\hbar}} b_0(t') \right\}$$

and plug in (1)

$$\frac{d b_0(t)}{dt} = - \sum_k \frac{U_k^2}{\hbar^2} \int_0^t dt' \left\{ e^{-i \frac{(\epsilon_k - \epsilon_0 - \hbar\omega)(t-t')}{\hbar}} b_0(t') \right\} \quad \text{--- (3)}$$

Note that if the k dependence of U_k^2 is not strong, the

Summation over k will give something close to a delta function in $(t-t')$ {i.e. $\delta(t-t')$ }. What this means is that the final result depends on values of $b_0(t')$ close to $b_0(t)$.

Therefore, we can let $b_0(t') \approx b_0(t)$ and remove it from the integral.

$$\frac{db_0(t)}{dt} = - \sum_k \frac{U_k^2}{\hbar^2} \int_0^t dt' \left\{ e^{-i \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right) (t-t')} \right\} b_0(t).$$

$$\Rightarrow \frac{d|b_0(t)|^2}{dt} = - 2 \operatorname{Re} \left\{ \sum_k \frac{U_k^2}{\hbar^2} \int_0^t dt' \left\{ e^{-i \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right) (t-t')} \right\} \right\} |b_0(t)|^2$$

$$2 \operatorname{Re} \left\{ \sum_k \frac{U_k^2}{\hbar^2} \int_0^t dt' e^{-i \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right) (t-t')} \right\}$$

$$= 2 \sum_k \frac{U_k^2}{\hbar^2} \frac{\sin \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} t \right)}{\left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right)}$$

Consider the function $\frac{\sin xt}{x}$. Its width is $\approx \frac{2\pi}{t}$ in x -space.

Note that $\int_{-\infty}^{\infty} dx \frac{\sin xt}{x} = \pi$ and $\frac{\sin xt}{x} \Big|_{x=0} = t$

As t becomes large (large compared to the relative energy level spacings $\Delta\epsilon_k$ of the upper states i.e. $\frac{\Delta\epsilon_k t}{\hbar} \gg 2\pi$)

This is because the width of the $\frac{\sin \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right) t}{\left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right)}$ function in the $(\epsilon_k - \epsilon_0 - \hbar\omega)$ space is $\frac{2\pi\hbar}{t}$ then we can replace

$$\frac{\sin \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right) t}{\left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right)} \text{ by } \pi \delta \left(\frac{\epsilon_k - \epsilon_0 - \hbar\omega}{\hbar} \right) = \pi \hbar \delta(\epsilon_k - \epsilon_0 - \hbar\omega).$$

So then we get:

$$\frac{d |b_0(t)|^2}{dt} = -\gamma |b_0(t)|^2$$

$$\text{where } \gamma = \frac{2\pi}{\hbar} \sum_k U_k^2 \delta(\epsilon_k - \epsilon_0 - \hbar\omega)$$

$$2.2 \quad U = \frac{\hbar\Omega R}{2}$$

$$a) \quad \hat{H}(t) = \epsilon_1 \hat{N}_1 + \epsilon_2 \hat{N}_2 - U \left[e^{-i\omega t} \hat{\sigma}_+ + e^{i\omega t} \hat{\sigma}_- \right]$$

In the Heisenberg picture:

$$\hat{H}(t) = \epsilon_1 \hat{N}_1(t) + \epsilon_2 \hat{N}_2(t) - U \left[e^{-i\omega t} \hat{\sigma}_+(t) + e^{i\omega t} \hat{\sigma}_-(t) \right]$$

$$\begin{aligned} i\hbar \frac{d\hat{N}_1(t)}{dt} &= [\hat{N}_1(t), \hat{H}(t)] \\ &= -U e^{-i\omega t} [\hat{N}_1(t), \hat{\sigma}_+(t)] - U e^{i\omega t} [\hat{N}_1(t), \hat{\sigma}_-(t)] \\ &= U e^{-i\omega t} \hat{\sigma}_+(t) - U e^{i\omega t} \hat{\sigma}_-(t) \end{aligned}$$

$$\begin{aligned} i\hbar \frac{d\hat{\sigma}_+(t)}{dt} &= [\hat{\sigma}_+(t), \hat{H}(t)] \\ &= \epsilon_1 [\hat{\sigma}_+(t), \hat{N}_1(t)] + \epsilon_2 [\hat{\sigma}_+(t), \hat{N}_2(t)] \\ &\quad - U e^{i\omega t} [\hat{\sigma}_+(t), \hat{\sigma}_-(t)] \\ &= -(\epsilon_2 - \epsilon_1) \hat{\sigma}_+(t) - U e^{i\omega t} [\hat{N}_2(t) - \hat{N}_1(t)] \end{aligned}$$

$$\text{Also, } \left(i\hbar \frac{d\hat{\sigma}_+(t)}{dt} \right)^\dagger = i\hbar \frac{d\hat{\sigma}_-(t)}{dt} \quad \text{since } (\hat{\sigma}_+(t))^\dagger = \hat{\sigma}_-(t).$$

$$\text{and } \frac{d\hat{N}_2(t)}{dt} = -\frac{d\hat{N}_1(t)}{dt}.$$

b) This is pretty straight forward so I will skip it.

c) We have:

$$\frac{d\hat{N}_1(t)}{dt} = -i\frac{U}{\hbar} [\hat{\sigma}_{++}(t) - \hat{\sigma}_{--}(t)]$$

$$\frac{d\hat{N}_2(t)}{dt} = i\frac{U}{\hbar} [\hat{\sigma}_{++}(t) - \hat{\sigma}_{--}(t)]$$

If $\Delta\hat{N}(t) = \hat{N}_2(t) - \hat{N}_1(t)$ then

$$\frac{d\Delta\hat{N}(t)}{dt} = i\frac{2U}{\hbar} \Delta\hat{\sigma}(t) \quad \left. \vphantom{\frac{d\Delta\hat{N}(t)}{dt}} \right\} \text{ where } \Delta\hat{\sigma}(t) = \hat{\sigma}_{++}(t) - \hat{\sigma}_{--}(t)$$

$$\text{Also } \frac{d\Delta\hat{\sigma}(t)}{dt} = i\frac{2U}{\hbar} \Delta\hat{N}(t)$$

$\Delta\hat{N}(t)$ and $\Delta\hat{\sigma}(t)$ are the coupled quantities. Diff. the equation for $\Delta\hat{N}(t)$ and use the equation for $\Delta\hat{\sigma}(t)$ to get:

$$\frac{d^2}{dt^2} \Delta\hat{N}(t) = -\left(\frac{2U}{\hbar}\right)^2 \Delta\hat{N}(t) = -\Omega_R^2 \Delta\hat{N}(t).$$

$$\Rightarrow \Delta\hat{N}(t) = \hat{A} \cos(\Omega_R t) + \hat{B} \sin \Omega_R t$$

Boundary conditions:

$$\Delta\hat{N}(t=0) = \hat{A} = \hat{N}_2 - \hat{N}_1 = \Delta\hat{N}$$

$$\left. \frac{d\Delta\hat{N}(t)}{dt} \right|_{t=0} = \Omega_R \hat{B} = i\frac{2U}{\hbar} \Delta\hat{\sigma}(t=0) = i\Omega_R (\hat{\sigma}_+ - \hat{\sigma}_-)$$

$$\Rightarrow \Delta\hat{N}(t) = \hat{N}_2(t) - \hat{N}_1(t) = \Delta\hat{N} \cos(\Omega_R t) + i(\hat{\sigma}_+ - \hat{\sigma}_-)$$

$$\text{Also. } \hat{N}_2(t) + \hat{N}_1(t) = \hat{N}_2 + \hat{N}_1 \quad \text{since } \frac{d}{dt} (\hat{N}_2(t) + \hat{N}_1(t)) = 0$$

so

$$\begin{aligned}\hat{N}_1(t) &= \frac{(\hat{N}_2(t) + \hat{N}_1(t)) - \Delta \hat{N}(t)}{2} = \frac{(\hat{N}_2 + \hat{N}_1) - \Delta \hat{N}(t)}{2} \\ &= \hat{N}_1 \cos^2\left(\frac{\Omega_R t}{2}\right) + \hat{N}_2 \sin^2\left(\frac{\Omega_R t}{2}\right) - \frac{i}{2} (\hat{\sigma}_+ - \hat{\sigma}_-) \sin(\Omega_R t).\end{aligned}$$

d). $\hat{P}(t=0) = |e_2\rangle\langle e_2| = \hat{N}_2$.

Note that $\hat{N}_1 \cdot \hat{N}_2 = 0$ $\hat{N}_2 \cdot \hat{N}_2 = \hat{N}_2$ $\hat{N}_2 \cdot \hat{\sigma}_- = 0$

and $\hat{N}_2 \cdot \hat{\sigma}_+ = \hat{\sigma}_+$

$$\begin{aligned}\Rightarrow \text{Tr}\{\hat{P}(t=0) \hat{N}_1(t)\} &= \text{Tr}\{\hat{N}_2 \cdot \hat{N}_1(t)\} = \text{Tr}\left\{\hat{N}_2 \sin^2\left(\frac{\Omega_R t}{2}\right) - \frac{i}{2} \hat{\sigma}_+ \sin(\Omega_R t)\right\} \\ &= \sin^2\left(\frac{\Omega_R t}{2}\right).\end{aligned}$$

2.3

$$U = \frac{\hbar \Omega_R}{2}$$

a) Choose a vector perpendicular to $\vec{\Omega}$ (and therefore in the plane of rotation) that is in the x-z plane. This vector should have unit magnitude. I choose it to be

$$\frac{\frac{\Delta}{\hbar} \hat{x} + \Omega_R \hat{z}}{\sqrt{\Omega_R^2 + \left(\frac{\Delta}{\hbar}\right)^2}} = \hat{n}$$

then $\cos \theta = \hat{z} \cdot \hat{n} = \frac{\Omega_R}{\sqrt{\Omega_R^2 + \left(\frac{\Delta}{\hbar}\right)^2}} = \frac{\Omega_R}{|\vec{\Omega}|}$

b) The population difference is the projection of $\vec{V}(t)$ on the z -axis. The max. value of this projection is obvious from the figure to be $\cos(2\theta)$.

$$\cos 2\theta = 2 \cos^2 \theta - 1 = 2 \frac{\Omega_R^2}{|\vec{R}|^2} - 1 = \frac{\Omega_R^2 - (\Delta/k)^2}{|\vec{R}|^2}$$

From Lecture notes:

$$\langle e_1 | \psi(t) \rangle^2 = P_{11}(t) = \frac{1}{2} \left[1 + \frac{(\Delta/k)^2}{|\vec{R}|^2} + \frac{(2U/k)^2}{|\vec{R}|^2} \cos |\vec{R}|t \right]$$

and $P_{22}(t) = 1 - P_{11}(t)$

So $P_{22}(t) - P_{11}(t) = 1 - 2P_{11}(t)$

$$= - \frac{(\Delta/k)^2}{|\vec{R}|^2} - \frac{(2U/k)^2}{|\vec{R}|^2} \cos |\vec{R}|t$$

$$P_{22}(t) - P_{11}(t) \Big|_{\max} = \frac{(2U/k)^2 - (\Delta/k)^2}{|\vec{R}|^2} = \frac{\Omega_R^2 - (\Delta/k)^2}{|\vec{R}|^2}$$

So they agree.

c) First take

$$|\psi(t=0)\rangle = \frac{1}{\sqrt{2}} [|e_1\rangle + i |e_2\rangle]$$

$$\hat{P}(t=0) = |\psi(t=0)\rangle \langle \psi(t=0)| = \frac{1}{2} \left\{ |e_1\rangle \langle e_1| + |e_2\rangle \langle e_2| - i |e_1\rangle \langle e_2| + i |e_2\rangle \langle e_1| \right\}$$

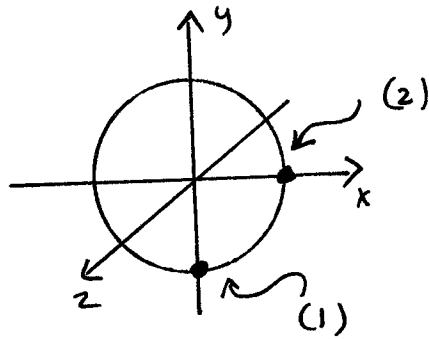
$$= \begin{bmatrix} 1/2 & -i/2 \\ i/2 & 1/2 \end{bmatrix}$$

⇒

$$V_x(t=0) = 0$$

$$V_y(t=0) = -1$$

$$V_z(t=0) = 0$$



Then take :

$$|\psi(t=0)\rangle = \frac{1}{\sqrt{2}} [|e_1\rangle + |e_2\rangle]$$

$$\hat{J}(t=0) = |\psi(t=0)\rangle \langle \psi(t=0)| = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

$$V_x(t=0) = 1$$

$$V_y(t=0) = 0$$

$$V_z(t=0) = 0$$

d) For initial state (1):

axis of rotation: the x-axis

plane of rotation: the y-z plane at x=0

direction of rotation: clockwise when looking at the y-z plane from positive x-axis.

For initial state (2):

The state vector $\vec{V}(t)$ does not change with time!