

1. A certain LTI system has impulse response  $h$  whose specification is

$$h(n) = \begin{cases} 7^{-n} & \text{if } 0 \leq n < 11 \\ 0 & \text{otherwise.} \end{cases}$$

- (a) What is  $\mathcal{D}_h$ , the set of all  $x \in \mathbb{F}^{\mathbb{Z}}$  for which  $h * x$  exists?  
 (b) Find the output  $S(x)$  of the system when the input is the signal  $x$  whose specification is

$$x(n) = 3 \text{ for all } n \in \mathbb{Z}.$$

- (c) Find  $S(u)$ , the *step response* of the system, which is the output of the system when its input is a unit step. What I'd like here are formulas for  $S(u)(n)$  for all  $n \in \mathbb{Z}$ .  
 (d) Suppose  $x \in \mathbb{F}^{\mathbb{Z}}$  has duration 13. What is the maximum possible duration for  $S(x)$ ?

2. Denote by  $S$  the system mapping for the causal sliding-window  $M$ -fold averager with  $M = 5$ .

- (a) Find a non-constant signal  $x \in \mathbb{F}^{\mathbb{Z}}$  for which  $S(x)(n) = 13$  for every  $n \in \mathbb{Z}$ .  
 (b) Show that  $\lim_{n \rightarrow \infty} S(x)(n) = 0$  for every left-sided signal  $x \in \mathbb{F}^{\mathbb{Z}}$ . Show also that  $\lim_{n \rightarrow -\infty} S(x)(n) = 0$  for every right-sided signal  $x \in \mathbb{F}^{\mathbb{Z}}$ .  
 (c) Find a signal  $x \in \mathbb{F}^{\mathbb{Z}}$  that doesn't have finite duration but that satisfies

$$\lim_{n \rightarrow \pm\infty} S(x)(n) = 0.$$

3. In each case I've described the input space  $X$  and system mapping  $S$  for some discrete-time I/O system. All of the systems are linear, but none is time-invariant. For each system, find an input signal  $x \in \mathbb{F}^{\mathbb{Z}}$  and a  $k_o \in \mathbb{Z}$  for which

$$S(\text{Shift}_{k_o}(x)) \neq \text{Shift}_{k_o}(S(x)).$$

(This problem is easier than it might appear — how about trying  $\delta$ ?)

- (a)  $X = \mathbb{F}^{\mathbb{Z}}$  and  $S(x)$  for every  $x \in X$  has specification

$$S(x)(n) = \begin{cases} \sum_{k=0}^n (k+1)x(k) & \text{if } n \geq 0 \\ 0 & \text{if } n < 0. \end{cases}$$

- (b)  $X = \mathbb{F}^{\mathbb{Z}}$  and  $S(x)$  for every  $x \in X$  has specification

$$S(x)(n) = \begin{cases} x(n) & \text{if } n \text{ is odd} \\ 0 & \text{if } n \text{ is even.} \end{cases}$$

- (c)  $X = \mathbb{F}^{\mathbb{Z}}$  and  $S(x)$  for every  $x \in X$  has specification

$$S(x)(n) = x(3n) \text{ for all } n \in \mathbb{Z}.$$

- (d)  $X = \mathbb{F}^{\mathbb{Z}}$  and  $S(x)$  for every  $x \in X$  is the constant signal with specification

$$S(x)(n) = \frac{1}{M} \sum_{k=0}^{M-1} x(k) \text{ for all } n \in \mathbb{Z},$$

where  $M$  is some given positive integer.

4. Explain why each of the systems in the previous problem is causal or not causal.
5. Suppose you have two LTI systems with system mappings  $S_1$  and  $S_2$  and respective impulse responses  $h_1$  and  $h_2$ . Suppose  $h_1 \in X_2$ , where  $X_2 = \mathcal{D}_{h_2}$  is the input space of the system with system mapping  $S_2$ . Let  $X$  be the set of all  $x \in X_1$  such that  $S_1(x) \in X_2$ , where  $X_1 = \mathcal{D}_{h_1}$  is the input space of the system with system mapping  $S_1$ .

- (a) Show that  $X$  contains all the finite-duration signals in  $\mathbb{F}^{\mathbb{Z}}$ . (Suggestion:  $X_1$  contains them all; the question is whether  $h_1 * x \in X_2$  whenever  $x$  has finite duration. Since  $h_1 \in X_2$ ,  $h_2 * h_1$  exists. Does  $h_2 * h_1 * x$  exist when  $x$  has finite duration?)
- (b) Show that the discrete-time system with input space  $X$  and system mapping  $S : X \rightarrow \mathbb{F}^{\mathbb{Z}}$  defined by

$$S(x) = S_2(S_1(x)) \text{ for all } x \in X$$

is LTI.

- (c) Show that the impulse response of the system in (b) is the convolution of  $h_1$  with  $h_2$ .

6. Suppose you take any two FIR systems and concatenate them as in the previous problem. Explain why, without any assumptions other than FIR-ness of the two systems, the concatenated system is an FIR system with input space  $X = \mathbb{F}^{\mathbb{Z}}$ .

7. Explain why each of the following causal LTI systems is or is not BIBO stable.

- (a) The system has impulse response  $h$  with specification

$$h(n) = 7^{-n}u(n) \text{ for all } n \in \mathbb{Z}.$$

- (b) The system has system mapping  $S$  with specification

$$S(x)(n) = \sum_{k=-\infty}^n 5^{(n-k)}x(k) \text{ for all } x \in \mathcal{D}_h \text{ and } n \in \mathbb{Z}.$$

Here,  $\mathcal{D}_h$  is the set of all  $x \in \mathbb{F}^{\mathbb{Z}}$  for which  $h * x$  exists, where  $h$  is the system's impulse response (which I'm not telling you).

- (c) The system has input space  $X = \mathbb{F}^{\mathbb{Z}}$  and system mapping

$$S(x) = 10^{53}x - 10^{13}\text{Shift}_{17}(x) \text{ for all } x \in X.$$

8. You can think of BIBO stability as imposing a continuity condition on the system mapping  $S$ . Specifically, show that if  $\{x_k\}$  is a sequence of bounded signals converging to a bounded signal  $x$  in the sense that

$$\lim_{k \rightarrow \infty} \|x_k - x\|_{\infty} = 0,$$

then  $S(x_k)$  converges to  $S(x)$  as  $k \rightarrow \infty$  in the sense that

$$\|S(x_k) - S(x)\|_{\infty} = 0$$

whenever  $S$  is the system mapping of a BIBO stable system.