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ECE 2200 and ENGRD 2220
Signals and Systems
Spring 2016
Problem Set 8

Due Friday April 22, 2016 at 5:00PM.

Location to turn in: "ECE 2200" box on Phillips Hall 2nd floor

1. Slightly modified version of McClellan, Schafer, Yoder Exercise 12.12 on p. 364. If $x(t)$ is the input and $y(t)$ is the output, a so-called half-wave rectifier is defined by

$$y(t) = \begin{cases} x(t), & x(t) > 0 \\ 0, & \text{otherwise} \end{cases} \quad (95)$$

Please show that the half-wave rectifier is a nonlinear system.

2. Slightly modified version of McClellan, Schafer, Yoder Exercise 12.13 on p. 365. Let $x(t) = \cos(\omega_c t)$. Let $y(t)$ be the output of the half-wave rectifier defined in Problem 1. Please show that the Fourier coefficients for $y(t)$ are

$$a_k = \begin{cases} \frac{\cos(\pi k/2)}{\pi(1-k^2)}, & k \neq \pm 1 \\ \frac{1}{4}, & k = \pm 1 \end{cases} \quad (96)$$

3. Please determine the inverse continuous-time Fourier transform of

$$H(\omega) = \frac{86 + 28j\omega - 2\omega^2}{24 + 10j\omega - \omega^2} \quad (97)$$

I suggest doing this via partial fraction expansion.

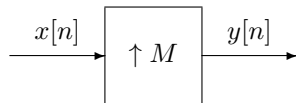
4. Please consider the differential equation

$$\frac{d^2 y}{dt^2} + 10 \frac{dy}{dt} + 24y(t) = 2x(t) + 8 \frac{dx}{dt} \quad (98)$$

with input $x(t)$ and output $y(t)$. What is the frequency response $H(\omega)$ (recall that if $x(t) \leftrightarrow X(\omega)$ and $y(t) \leftrightarrow Y(\omega)$ then the frequency response is $H(\omega) = Y(\omega)/X(\omega)$)?

5. This problem concerns oversampling Digital to Analog converters. Such converters are commonly used in CD players.

(a) Define an up-converter block by the following block diagram and equation:



$$y[n] = \begin{cases} x[n/M], & n = Ml \text{ for some } l \in \mathcal{Z} \\ 0, & \text{otherwise} \end{cases} \quad (99)$$

If $x[n]$ has Discrete-Time Fourier Transform $X(\Omega)$, then what is the Discrete-Time Fourier Transform of $y[n]$?

Answer:

$$Y(\Omega) = \sum_{n=-\infty}^{+\infty} y[n] \exp(-in\Omega) \quad (100)$$

$$= \sum_{n=-\infty, n=Ml}^{+\infty} y[n] \exp(-in\Omega) + \sum_{n=-\infty, n \neq Ml}^{+\infty} y[n] \exp(-in\Omega) \quad (101)$$

$$= \sum_{n=-\infty, n=Ml}^{+\infty} x[n/M] \exp(-in\Omega) + \sum_{n=-\infty, n \neq Ml}^{+\infty} 0 \exp(-in\Omega) \quad (102)$$

$$= \sum_{l=-\infty}^{+\infty} x[l] \exp(-iMl\Omega) \quad (103)$$

$$= \sum_{l=-\infty}^{+\infty} x[l] \exp(-il(M\Omega)) \quad (104)$$

$$= X(M\Omega). \quad (105)$$

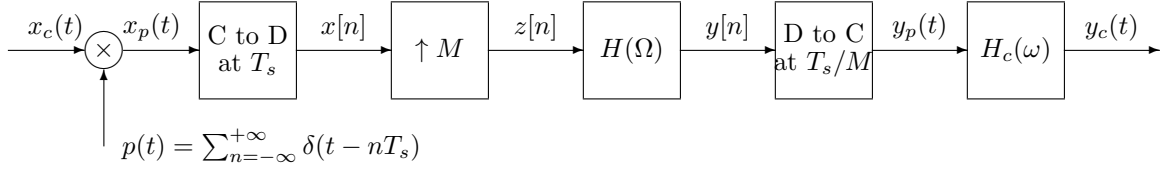
(b) Suppose that

$$X_0(\Omega) = \begin{cases} \bar{X}_0 (1 - |\Omega|/\pi), & -\pi \leq \Omega \leq \pi \\ 0, & \text{otherwise} \end{cases} \quad (106)$$

$$X(\Omega) = \sum_{k=-\infty}^{+\infty} X_0(\Omega + k2\pi). \quad (107)$$

Please plot $X(\Omega)$. Please plot the corresponding $Y(\Omega)$ for the case of $M = 8$.

(c) Please consider the following block diagram:



where

i. $x[n] = x_c(nT_s)$.

ii.

$$z[n] = \begin{cases} x[n/M], & n - Ml \text{ for some } l \in \mathcal{Z} \\ 0, & \text{otherwise} \end{cases}. \quad (108)$$

iii.

$$H_0(\Omega) = \begin{cases} 1, & -\pi/M \leq \Omega \leq \pi/M \\ 0, & \text{otherwise} \end{cases} \quad (109)$$

$$H(\Omega) = \sum_{k=-\infty}^{+\infty} H_0(\Omega + k2\pi). \quad (110)$$

iv. $z[n] \leftrightarrow Z(\Omega)$, $y[n] \leftrightarrow Y(\Omega)$, and $Y(\Omega) = H(\Omega)Z(\Omega)$.

v.

$$y_p(t) = \sum_{n=-\infty}^{+\infty} y[n] \delta(t - nT_s/M). \quad (111)$$

vi. $y_p(t) \leftrightarrow Y_P(\omega)$, $y_c(t) \leftrightarrow Y_c(\omega)$, and $Y(\omega) = H_c(\omega)Y_P(\omega)$.

For the case of

i.

$$X_c(\omega) = \begin{cases} \bar{X}_c (1 - |\omega|/\omega_X), & -\omega_X \leq \omega \leq \omega_X \\ 0, & \text{otherwise} \end{cases}. \quad (112)$$

- ii. $T_s < (1/2)(2\pi/\omega_X)$ and $\bar{X}_c = 1$.
- iii. $M = 8$.

please plot $X_c(\Omega)$, $X(\Omega)$, $Z(\Omega)$, and $Y(\Omega)$. What are the constraints on $H_c(\omega)$ such that $y_c(t) = x_c(t)$?

- (d) Why do the manufacturers of CD players often use this approach?
- (e) What is the impulse response $h[n]$ corresponding to the frequency response $H(\Omega)$? Probably you will agree with the statement that some approximation to this impulse response will be needed in order to build a practical system. Note, however, that in many play-back applications, a delay can be tolerated.