

$$H(z) = \frac{1 - az^{-1}}{(1 - b_1 z^{-1})(1 - b_2 z^{-1})}$$

$$(a) \quad \frac{Y(z)}{X(z)} = H(z) = \frac{1 - az^{-1}}{(1 - b_1 z^{-1})(1 - b_2 z^{-1})}$$

$$\Rightarrow (1 - b_1 z^{-1})(1 - b_2 z^{-1}) Y(z) = (1 - az^{-1}) X(z)$$

$$\Rightarrow (1 - (b_1 + b_2)z^{-1} + b_1 b_2 z^{-2}) Y(z) = (1 - az^{-1}) X(z)$$

$$\Rightarrow y[n] - (b_1 + b_2)y[n-1] + b_1 b_2 y[n-2] = x[n] - ax[n-1]$$

$$(b) \quad H(z) = \frac{1 - az^{-1}}{(1 - b_1 z^{-1})(1 - b_2 z^{-1})} \cdot \frac{z^2}{z^2}$$

$$= \frac{z(z-a)}{(z-b_1)(z-b_2)}$$

poles: $z = b_1, z = b_2$

(c) zeros: $z = 0, z = a$

(d) $x[n] = d^n$

pick $d = a =$ location of zero.

$d = 0 =$ location of second zero gives an input that is always zero.

(e) $|b_1| < |b_2|$. Do partial fraction expansion

$$H(z) = \frac{1 - az^{-1}}{(1 - b_1 z^{-1})(1 - b_2 z^{-1})} = \frac{A}{1 - b_1 z^{-1}} + \frac{B}{1 - b_2 z^{-1}}$$

$$A = \left. \frac{1 - az^{-1}}{1 - b_2 z^{-1}} \right|_{z=b_1} = \frac{1 - ab_1^{-1}}{1 - b_2 b_1^{-1}} = f_1$$

$$B = \left. \frac{1 - az^{-1}}{1 - b_1 z^{-1}} \right|_{z=b_2} = \frac{1 - ab_2^{-1}}{1 - b_1 b_2^{-1}} = f_2$$

$$H(z) = \frac{f_1}{1 - b_1 z^{-1}} + \frac{f_2}{1 - b_2 z^{-1}} \quad |b_1| < |b_2| \quad \text{p074 } \checkmark$$

A) Anticausal

$h_A[n] = -f_1 b_1^n u[-n-1] - f_2 b_2^n u[-n-1]$ BIBO stable if $|b_1| < 1$

B)

= no intersection

C) Neither

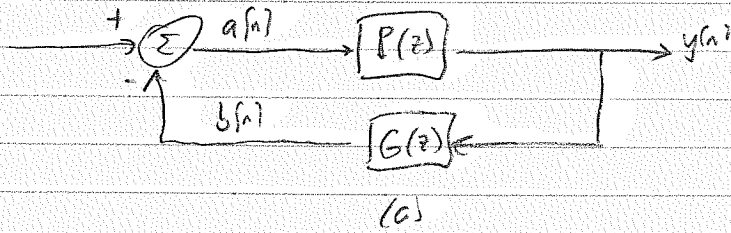
$h_C[n] = f_1 b_1^n u[n] - f_2 b_2^n u[-n-1]$ BIBO stable if $|b_1| < 1 < |b_2|$

D) Causal

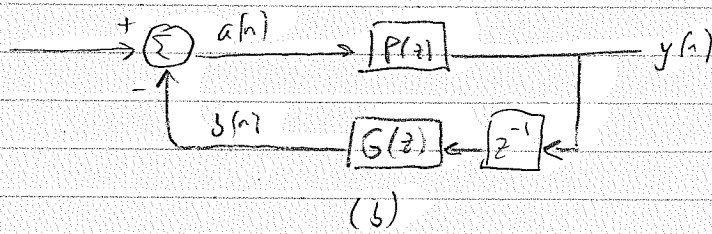
$h_C[n] = f_1 b_1^n u[n] + f_2 b_2^n u[n]$ BIBO stable if $|b_2| < 1$

(f) See answers for causal, anticausal, and neither in (e)

(g) See answers for BIBO stable in (e)



$$H_a(z) = \frac{P(z)}{1 + P(z)G(z)}$$



$$p[n] = \alpha^n u[n] \leftrightarrow P(z) = \frac{1}{1 - \alpha z^{-1}} \quad |\alpha| < |z|$$

$$g[n] = \beta \delta[n] \leftrightarrow G(z) = \beta \text{ for all } z.$$

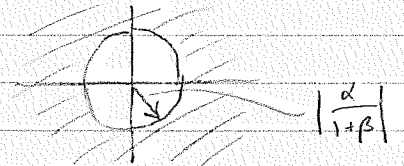
(a) Since $\rightarrow |z^{-1}| \rightarrow |G(z)| \rightarrow$ is equivalent to $\rightarrow |z^{-1}G(z)| \rightarrow$, it follows that

$$H_b(z) = \frac{P(z)}{1 + P(z)z^{-1}G(z)}$$

(b) $P(z)$ is BIBO unstable

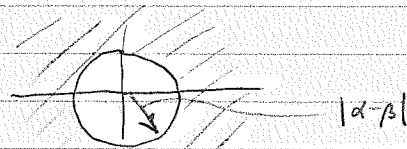
$$(c) \text{ and } (d) \quad H_a(z) = \frac{P(z)}{1 + P(z)G(z)} = \frac{\frac{1}{1 - \alpha z^{-1}}}{1 + \frac{1}{1 - \alpha z^{-1}} \beta} = \frac{1 - \alpha z^{-1}}{1 - \alpha z^{-1} + \beta}$$

$$= \frac{1}{(1 + \beta) - \alpha z^{-1}} = \frac{1}{1 + \beta} \frac{1}{1 - \frac{\alpha}{1 + \beta} z^{-1}}$$



$$H_b(z) = \frac{P(z)}{1 + P(z)z^{-1}G(z)} = \frac{\frac{1}{1 - \alpha z^{-1}}}{1 + \frac{1}{1 - \alpha z^{-1}} z^{-1} \beta} = \frac{1 - \alpha z^{-1}}{1 - \alpha z^{-1} + z^{-1} \beta}$$

$$= \frac{1}{1 - (\alpha - \beta) z^{-1}}$$



(e) H_a : BIBO stable $\Leftrightarrow \left| \frac{\alpha}{1 + \beta} \right| < 1 \Leftrightarrow |\alpha| < |1 + \beta|$

H_b : BIBO stable $\Leftrightarrow |\alpha - \beta| < 1$

(f) $\alpha = 2, \beta = 5 \Rightarrow \begin{cases} |\alpha| < |1 + \beta| \text{ is true since LHS} = 2, \text{ RHS} = 6 \\ |\alpha - \beta| < 1 \text{ is false since } |\alpha - \beta| = |2 - 5| = |-3| = 3 \end{cases}$

$$a) h_1[n] = \left(\frac{1}{2}\right)^n u[n+1]$$

Starts at $n=-1 \Rightarrow$ Neither causal nor anticausal

is BIBO stable

$$b) y_2[n] = \sum_{k=-1}^3 x_2[n-k]$$

to compute $h_2[n]$, set $x_2[n] = \delta[n]$:

$$h_2[n] = \sum_{k=-1}^3 \delta[n-k] = \dots$$

Starts at $n=-1 \Rightarrow$ Neither causal nor anticausal

is BIBO stable

$$c) h_3[n] = 2^{|n|}$$

$h_3[n]$ is always non zero — Neither causal nor anticausal

not BIBO stable: $\sum_{n=-\infty}^{+\infty} |h_3[n]| = \sum_{n=-\infty}^{+\infty} 2^{|n|} = +\infty$

$$d) h_4[n] = (-1)^n u[n]$$

Causal

not BIBO stable: $\sum_{n=-\infty}^{+\infty} |h_4[n]| = \sum_{n=0}^{\infty} |-1|^n = \sum_{n=0}^{\infty} 1 = \infty$

$$e) M \in \mathbb{Z}, n > 0$$

$$y_5[n] = \begin{cases} x_5[n/M], & n = Ml \text{ for some } l \in \mathbb{Z} \\ 0, & \text{otherwise.} \end{cases}$$

Is linear.

Is not time invariant: Compare $x_5[n] = \delta[n] \Rightarrow y_5[n] = \delta[n]$ with $x_5[n] = \delta[n-1] \Rightarrow y_5[n] = \delta[n-M]$. The two x_5 are shifted by 1 in time but the two y_5 are shifted by M in time.